

**AMENDMENTS TO THE CLAIMS:**

This listing of claims will replace all prior versions and listings of claims in the application.

**LISTING OF CLAIMS:**

1. (Currently Amended) A luminance dynamic range system, comprising:

an image processing module for transforming an input image into a luminance component  $L_{in}$  and chrominance components,  $C_1$  and  $C_2$ ;

a spatial low pass filter, responsive to  $L_{in}$  for outputting a filtered luminance component  $L_f$ , wherein  $L_f$  is a function only of  $L_{in}[:,:]$  wherein the low pass filter is small enough that shadow regions are passed through as low luminance, and large enough to filter out detail in high-contrast regions; and

a luminance compression module for gamut mapping that varies across different parts of the input image, spatially adapting the luminance compression function according to local image characteristics in such a manner as to preserve both shadow detail and overall image contrast, responsive to  $L_f$  and  $L_{in}$  for performing luminance compression on the input component  $L_{in}$  to output a compressed luminance signal  $L_{out}$  that is within an achievable luminance range of an output device; wherein the luminance compression module combines two compression functions  $L_{comp1}(L_{in})$  and  $L_{comp2}(L_{in})$  via a blending function  $\alpha(L_f)$ ; wherein the function  $L_{comp1}$  is optimized for preserving overall image contrast and the function  $L_{comp2}$  is optimized for preserving shadow detail; wherein  $L_{comp1}(L_{in})$ ,  $L_{comp2}(L_{in})$  and  $\alpha(L_f)$  are all 1-dimensional functions only of  $L_{in}$ ; and wherein  $L_{comp1}(L_{in})$  and  $L_{comp2}(L_{in})$  are both designed such that the overall compression function is spatially smooth and to map the luminance dynamic range of ~~an~~ the input image to the more limited dynamic range of ~~an~~ the output device.

2. (Canceled).

3. (Previously Amended) The system of claim 1, wherein  $L_{out}$  is computed

according to the relationship  $L_{out} = \alpha(L_f) L_{comp1}(L_{in}) + (1 - \alpha(L_f)) L_{comp2}(L_{in})$ .

4. (Previously Amended) The system of claim 1, wherein  $\alpha(L_f)$  is a piecewise linear function, determined by two breakpoints,  $B_1$  and  $B_2$ .

5. (Previously Amended) The system of Claim 1, wherein function  $L_{comp1}$  is optimized for preserving overall image contrast.

6. (Previously Amended) The system of Claim 1, wherein function  $L_{comp2}$  is optimized for preserving shadow detail.

7. (Original) The system of claim 4, wherein:

$\alpha(L_f) = 0$  for values of  $L_f$  between 0 and  $B_1$ ;

$\alpha(L_f)$  increases linearly from 0 to 1 for values of  $L_f$  from  $B_1$  to  $B_2$ ; and

$\alpha(L_f) = 1$  for values of  $L_f$  between  $B_2$  and  $L_{max}$ ,

where  $L_{max}$  is a maximum luminance achievable by the output device.

8. (Canceled).

9. (Original) The system of claim 1, wherein the low pass filter comprises a constant weight filter.

10. (Currently Amended) The system of claim 1, wherein the input image is down-sampled prior to filtering and upsampled and interpolated after filtering.

11. (Original) The system of claim 1, further comprising a color correction module for transforming  $L_{out}$ ,  $C_1$  and  $C_2$  to CMYK for printing.

12. (Currently Amended) A method for luminance dynamic range

mapping, comprising:

transforming an input image into a luminance component  $L_{in}$  and chrominance components,  $C_1$  and  $C_2$ ;

spatially low pass filtering  $L_{in}$  into a filtered luminance component  $L_f$ , wherein  $L_f$  is a function only of  $L_{in}[:,:]$  wherein the low pass filtering is small enough that shadow regions are passed through as low luminance, and large enough to filter out detail in high-contrast regions; and

processing  $L_f$  and  $L_{in}$  through a luminance compression module for gamut mapping that varies across different parts of the input image, spatially adapting the luminance compression function according to local image characteristics in such a manner as to preserve both shadow detail and overall image contrast, to obtain a compressed luminance signal  $L_{out}$  that is within an achievable luminance range of an output device; wherein the processing step comprises combining two compression functions  $L_{comp1}(L_{in})$  and  $L_{comp2}(L_{in})$  via a blending function  $\alpha(L_f)$ ; wherein the function  $L_{comp1}$  is optimized for preserving overall image contrast and the function  $L_{comp2}$  is optimized for preserving shadow detail; wherein  $L_{comp1}(L_{in})$ ,  $L_{comp2}(L_{in})$  and  $\alpha(L_f)$  are all 1-dimensional functions only of  $L_{in}$ ; and wherein  $L_{comp1}(L_{in})$  and  $L_{comp2}(L_{in})$  are both designed such that the overall compression function is spatially smooth and to map the luminance dynamic range of ~~an~~ the input image to the more limited dynamic range of ~~an~~ the output device.

13. (Canceled).

14. (Previously Amended) The method of claim 12, wherein  $L_{comp1}(L_{in})$  and  $L_{comp2}(L_{in})$  are combined according to the relationship  $L_{out} = \alpha(L_f) L_{comp1}(L_{in}) + (1 - \alpha(L_f)) L_{comp2}(L_{in})$ .

15. (Previously Amended) The method of claim 12, wherein  $\alpha(L_f)$  is a piecewise linear function, determined by two breakpoints,  $B_1$  and  $B_2$ .

16. (Previously Amended) The method of Claim 12, wherein function  $L_{comp1}$  is optimized for preserving overall image contrast.

17. (Previously Amended) The method of Claim 12, wherein function  $L_{comp2}$  is optimized for preserving shadow detail.

18. (Original) The method of claim 15, wherein:

$\alpha(L_f) = 0$  for values of  $L_f$  between 0 and  $B_1$ ;

$\alpha(L_f)$  increases linearly from 0 to 1 for values of  $L_f$  from  $B_1$  to  $B_2$ ; and

$\alpha(L_f) = 1$  for values of  $L_f$  between  $B_2$  and  $L_{max}$ ,

where  $L_{max}$  is a maximum luminance achievable by the output device.

19. (Canceled).

20. (Original) The method of claim 12, wherein the spatial low pass filtering comprises applying a constant weight filter.

21. (Original) The method of claim 12, further comprising down-sampling the input image prior to filtering and upsampling and interpolating the input image after filtering.

22. (Original) The method of claim 12, further comprising applying a color correction for transforming  $L_{out}$ ,  $C_1$  and  $C_2$  to CMYK for printing.